

I Year I Semester
Code: 17ME101

L T P C
3 1 0 3

ENGINEERING MECHANICS

UNIT – I

Objectives: The students are to be exposed to the concepts of system of force, direction and its application and concept of free body diagrams, system of equilibrium of forces.

Introduction to Engg. Mechanics – Basic Concepts.

Systems of Forces: Coplanar Concurrent Forces – Resultant, Triangles Law, Polygon's Law, Equilibrium of Systems of Forces: Free Body Diagrams, Equations of Equilibrium of Coplanar Systems, Lami's Theorem, Graphical method for the equilibrium of coplanar forces, Converse of the law of Triangle of forces, converse of the law of polygon of forces condition of equilibrium.

UNIT – II

Objectives: The students are to be exposed to application of moment of forces, couples, concepts of friction and basis idea on plane trusses.

Moment of Force and its Application – Varignon's Theorem – Couples and Resultant of Force Systems. Spatial Systems for concurrent forces – Resultant, Equilibrium of particle in space, Spatial Systems for moment of forces.

Friction: Introduction, limiting friction and impending motion, coulomb's laws of dry friction, coefficient of friction, cone of friction.

UNIT – III

Objectives : The students are to be exposed to concepts of centre of gravity.

Centroid: Centroids of simple figures (from basic principles) – Centroids of Composite Figures

Centre of Gravity: Centre of gravity of simple body (from basic principles), centre of gravity of composite bodies, Pappus theorems.

UNIT IV

Objective: The students are to be exposed to concepts of moment of inertia and polar moment of inertia including transfer methods and their applications.

Area moments of Inertia: Definition – Polar Moment of Inertia, Transfer Theorem, Moments of Inertia of Composite Figures, Products of Inertia, Transfer Formula for Product of Inertia.

Mass Moment of Inertia:

Moment of Inertia of Masses, Transfer Formula for Mass Moments of Inertia, mass moment of inertia of composite bodies.

UNIT – V

Objectives: The students are to be exposed to motion in straight line and in curvilinear paths, its velocity and acceleration computation and methods of representing plane

motion. Kinematics: Rectilinear and Curve linear motions – Velocity and Acceleration – Motion of Rigid Body – Types and their Analysis in Planar Motion.

Kinetics: Analysis as a Particle and Analysis as a Rigid Body in Translation– Central Force Motion – Equations of Plane Motion – Fixed Axis Rotation – Rolling Bodies.

UNIT – VI

Objectives: The students are to be exposed to concepts of work, energy and particle motion

Work – Energy Method: Equations for Translation, Work-Energy Applications to Particle Motion, Connected System-Fixed Axis Rotation and Plane Motion. Impulse momentum method.